

DIGITAL COMMUNICATIONS (cont.)

- For $\mu_1 > \mu_0$, P_e is given by

$$P_e = Q\left(\frac{\mu_1 - \mu_0}{2\sigma}\right).$$

If $\mu_1 < \mu_0$, it is easy to show by a symmetry argument (swapping μ_0 and μ_1) that

$$P_e = Q\left(\frac{\mu_0 - \mu_1}{2\sigma}\right).$$

Thus

$$\boxed{P_e = Q\left(\frac{|\mu_1 - \mu_0|}{2\sigma}\right)} \quad (1)$$

- **Minimizing P_e and Maximizing SNR:**

Since $Q(\cdot)$ is a monotonically decreasing function, the smallest value of P_e is obtained when $\frac{|\mu_1 - \mu_0|}{2\sigma}$ is maximized, or equivalently if the following quantity ρ is maximized.

$$\rho = \frac{|\mu_1 - \mu_0|^2}{\sigma^2}.$$

Note that ρ is a measure of the *signal-to-noise* ratio at the output of the filter.

Recall that

$$\mu_i = \int_{-\infty}^{\infty} h(\xi) s_i(T - \xi) d\xi, \quad i = 0, 1, \quad \text{and} \quad \sigma^2 = \frac{N_0}{2} \int_{-\infty}^{\infty} [h(\xi)]^2 d\xi$$

Thus

$$\rho = \frac{\left[\int_{-\infty}^{\infty} h(\xi) [s_1(T - \xi) - s_0(T - \xi)] d\xi \right]^2}{\frac{N_0}{2} \int_{-\infty}^{\infty} [h(\xi)]^2 d\xi} \quad (2)$$

- **Optimizing the filter $h(\cdot)$**

Our goal is to find $h(t)$ that maximizes ρ . This maximization is facilitated by the Cauchy-Schwarz inequality.

Cauchy-Schwarz (C-S) Inequality: For finite energy signals $x_1(t)$ and $x_2(t)$

$$\left[\int_{-\infty}^{\infty} x_1(t) x_2(t) dt \right]^2 \leq \int_{-\infty}^{\infty} [x_1(t)]^2 dt \int_{-\infty}^{\infty} [x_2(t)]^2 dt$$

with equality iff $x_2(t) = \alpha x_1(t)$ for some real number α .

Applying the C-S inequality to $h(\xi)$ and $[s_1(T - \xi) - s_0(T - \xi)]$ we get

$$\left[\int_{-\infty}^{\infty} h(\xi)[s_1(T - \xi) - s_0(T - \xi)]d\xi \right]^2 \leq \int_{-\infty}^{\infty} [h(\xi)]^2 d\xi \int_{-\infty}^{\infty} [s_1(T - \xi) - s_0(T - \xi)]^2 d\xi .$$

Dividing both sides by $\frac{N_0}{2} \int_{-\infty}^{\infty} [h(\xi)]^2 d\xi$, we get the following inequality for ρ of (2).

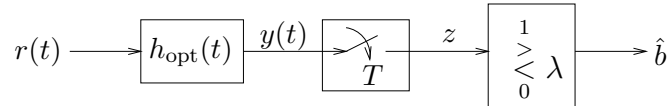
$$\rho = \frac{\left[\int_{-\infty}^{\infty} h(\xi)[s_1(T - \xi) - s_0(T - \xi)]d\xi \right]^2}{\frac{N_0}{2} \int_{-\infty}^{\infty} [h(\xi)]^2 d\xi} \leq \frac{2}{N_0} \int_{-\infty}^{\infty} [s_1(T - \xi) - s_0(T - \xi)]^2 d\xi$$

with equality iff $h(\xi) = \alpha[s_1(T - \xi) - s_0(T - \xi)]$. Without loss of generality we can set $\alpha = 1$, since scaling the filter does not affect ρ . Thus ρ is maximized by choosing

$$\boxed{h(t) = h_{\text{opt}}(t) = s_1(T - t) - s_0(T - t)}$$

This filter $h_{\text{opt}}(t)$ is also called the *matched filter*. Note that $h_{\text{opt}}(t)$ is obtained by “flipping” the difference signal $[s_1(t) - s_0(t)]$ in the interval $[0, T]$ around $t = T/2$. Thus $h_{\text{opt}}(t) = 0$ for $t < 0$ and $t > T$. This means that the optimum filter is *causal*.

We have now optimized both the decision device and the filter, and the optimum linear receiver is given by:

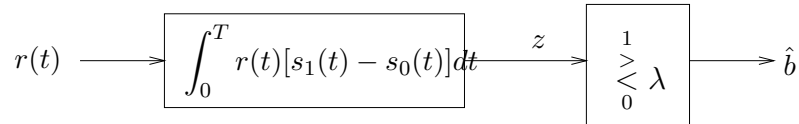


• Optimum Receiver as a Correlation Receiver

For the optimum linear receiver shown above

$$\begin{aligned} z = y(T) &= \int_{-\infty}^{\infty} r(T - \xi)h_{\text{opt}}(\xi)d\xi = \int_0^T r(T - \xi)h_{\text{opt}}(\xi)d\xi \\ &= \int_0^T r(T - \xi)[s_1(T - \xi) - s_0(T - \xi)]d\xi \stackrel{T - \xi = t}{=} \int_0^T r(t)[s_1(t) - s_0(t)]dt \end{aligned}$$

Thus an alternative way to construct the optimum receiver is to produce z by correlating $r(t)$ with the difference $s_1(t) - s_0(t)$. This correlator implementation is shown below.



• Performance of the Optimum Receiver

For the optimum receiver

$$\mu_{i,\text{opt}} = \int_0^T s_i(t)[s_1(t) - s_0(t)] dt, \quad i = 0, 1$$

and hence

$$\mu_{1,\text{opt}} - \mu_{0,\text{opt}} = \int_0^T [s_1(t) - s_0(t)]^2 dt = d > 0.$$

where d is the “squared distance” between the signals $s_1(t)$ and $s_0(t)$ and is defined by

$$d \stackrel{\text{def}}{=} \int_0^T [s_1(t) - s_0(t)]^2 dt$$

Since $\mu_{1,\text{opt}} - \mu_{0,\text{opt}} > 0$, the ML decision rule for the optimum receiver is

$$\boxed{z \begin{matrix} > \\ < \\ > \\ < \\ > \\ < \end{matrix} \lambda_{\text{opt}}}$$

where

$$\lambda_{\text{opt}} = \frac{\mu_{0,\text{opt}} + \mu_{1,\text{opt}}}{2} = \frac{1}{2} \int_0^T [s_1(t) + s_0(t)] [s_1(t) - s_0(t)] dt = \frac{1}{2} \int_0^T [s_1^2(t) - s_0^2(t)] dt = \frac{\mathcal{E}_1 - \mathcal{E}_0}{2}$$

Also, the error probability for the optimum receiver is

$$P_{e,\text{opt}} = Q\left(\frac{\mu_{1,\text{opt}} - \mu_{0,\text{opt}}}{2\sigma_{\text{opt}}}\right) = Q\left(\frac{d}{2\sigma_{\text{opt}}}\right)$$

where

$$\sigma_{\text{opt}}^2 = \frac{N_0}{2} \int_{-\infty}^{\infty} [h_{\text{opt}}(\xi)]^2 d\xi = \dots = \frac{N_0}{2} [\mu_{1,\text{opt}} - \mu_{0,\text{opt}}] = \frac{N_0}{2} d.$$

Thus

$$\boxed{P_{e,\text{opt}} = Q\left(\sqrt{\frac{d}{2N_0}}\right)}$$

Special Cases

In the following, we use $\bar{\mathcal{E}}$ to denote the average signal energy $\frac{\mathcal{E}_0 + \mathcal{E}_1}{2}$.

◦ *On-Off Keying:* $s_1(t) \neq 0, s_0(t) = 0 \Rightarrow \mathcal{E}_1 > 0, \mathcal{E}_0 = 0, \bar{\mathcal{E}} = \mathcal{E}_1/2$.

$$d = \int_0^T [s_1(t)]^2 dt = \mathcal{E}_1, \lambda_{\text{opt}} = \frac{\mathcal{E}_1}{2}, \text{ and } P_{e,\text{opt}} = Q\left(\sqrt{\frac{\mathcal{E}_1}{2N_0}}\right) = Q\left(\sqrt{\frac{\bar{\mathcal{E}}}{N_0}}\right)$$

◦ *Antipodal Signaling:* $s_1(t) = s(t), s_0(t) = -s(t) \Rightarrow \mathcal{E}_0 = \mathcal{E}_1 = \mathcal{E} = \bar{\mathcal{E}}$.

$$d = \int_0^T [2s(t)]^2 dt = 4\mathcal{E}, \lambda_{\text{opt}} = \frac{\mathcal{E}_1 - \mathcal{E}_0}{2} = 0, \text{ and } P_{e,\text{opt}} = Q\left(\sqrt{\frac{2\mathcal{E}}{N_0}}\right) = Q\left(\sqrt{\frac{2\bar{\mathcal{E}}}{N_0}}\right)$$

◦ *Orthogonal*: $\mathcal{E}_0 = \mathcal{E}_1 = \mathcal{E} = \bar{\mathcal{E}}$ and $\int_0^T s_0(t)s_1(t)dt = 0$

$$d = \mathcal{E}_0 + \mathcal{E}_1 - 2 \int_0^T s_0(t)s_1(t) dt = 2\mathcal{E}, \quad \lambda_{\text{opt}} = \frac{\mathcal{E}_1 - \mathcal{E}_0}{2} = 0,$$

and

$$P_{e,\text{opt}} = Q\left(\sqrt{\frac{\mathcal{E}}{N_0}}\right) = Q\left(\sqrt{\frac{\bar{\mathcal{E}}}{N_0}}\right)$$

- **Proposition** (Optimum Signal Set) Given constraints on the signal energies $\mathcal{E}_0 \leq \mathcal{E}$ and $\mathcal{E}_1 \leq \mathcal{E}$, the best signal set $\{s_0(t), s_1(t)\}$ is the *antipodal* signal set with $\mathcal{E}_0 = \mathcal{E}_1 = \mathcal{E}$.

Proof The set $\{s_0(t), s_1(t)\}$ that maximizes d , minimizes $P_{e,\text{opt}}$. Now,

$$d = \int_0^T [s_1(t) - s_0(t)]^2 dt = \mathcal{E}_0 + \mathcal{E}_1 - 2 \int_0^T s_0(t)s_1(t) dt$$

By Cauchy-Schwarz inequality

$$\int_0^T s_0(t)s_1(t) dt \geq -\sqrt{\mathcal{E}_0\mathcal{E}_1}$$

Thus

$$d \leq \mathcal{E}_0 + \mathcal{E}_1 + 2\sqrt{\mathcal{E}_0\mathcal{E}_1} \leq \mathcal{E} + \mathcal{E} + 2\sqrt{\mathcal{E}^2} = 4\mathcal{E}$$

But the bound of $4\mathcal{E}$ is achieved when we pick antipodal signals with $\mathcal{E}_0 = \mathcal{E}_1 = \mathcal{E}$. Hence, antipodal signals are optimum.

- **Binary Coherent Communication:** For binary coherent communication, the signal set is given by

$$s_i(t) = \sqrt{2} A_c a_i(t) \cos(2\pi f_c t + \theta_i(t) + \phi) p_T(t), \quad i = 0, 1$$

where $a_i(t)$ is the *amplitude* modulation term, and $\theta_i(t)$ is the *phase* modulation term. The communications is said to be coherent since knowledge of carrier frequency f_c and phase ϕ is assumed at the receiver.

- If $a_0(t) \neq a_1(t)$ and $\theta_0(t) = \theta_1(t)$, then we have *amplitude shift keying* (ASK).
- If $\theta_0(t) \neq \theta_1(t)$ and $a_0(t) = a_1(t)$, then we have *phase shift keying* (PSK)

- **Binary Phase Shift Keying (BPSK):** This is the simplest form of passband digital communications. Here $a_0(t) = a_1(t) = p_T(t)$ and

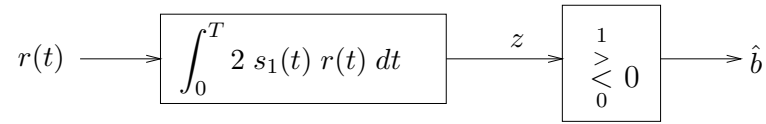
$$\theta_1(t) = 0, \quad \theta_0(t) = \pi \quad \text{for } 0 \leq t \leq T.$$

That is, the signal set is given by

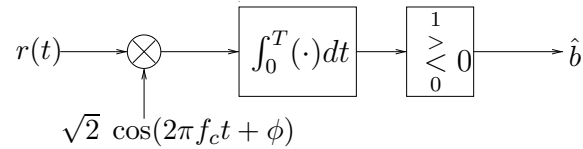
$$\begin{aligned} s_1(t) &= \sqrt{2} A_c p_T(t) \cos(2\pi f_c t + \phi) \\ s_0(t) &= \sqrt{2} A_c p_T(t) \cos(2\pi f_c t + \pi + \phi) = -\sqrt{2} A_c p_T(t) \cos(2\pi f_c t + \phi) = -s_1(t) \end{aligned}$$

This is an *antipodal* signal set. Note that BPSK can also be viewed as BASK with $a_1(t) = -a_0(t) = p_T(t)$ and $\theta_1(t) = \theta_0(t) = 0$.

- **Optimum Receiver for BPSK:** Since BPSK is antipodal signaling, the optimum receiver correlates $r(t)$ with $2s_1(t)$ and compares the output to 0 for decision making as shown below:



Now since $\int_0^T 2 s_1(t) r(t) dt = 2\sqrt{2} A_c \int_0^T \cos(2\pi f_c t + \phi) r(t) dt$ and scale factors do not affect the performance of the receiver, we may redraw the optimum receiver as shown below:



- **Performance of the Optimum Receiver for BPSK:**

$$\mathcal{E}_1 = \mathcal{E}_0 = \mathcal{E} = \int_0^T 2A_c^2 \cos^2(2\pi f_c t + \phi) dt = \dots = A_c^2 T + A_c^2 \left[\frac{\sin(4\pi f_c t + 2\phi) - \sin(2\phi)}{4\pi f_c} \right]$$

If f_c is chosen such that $f_c T = n$ for some integer n or if we ignore the “double frequency” terms, the second term on the RHS equals 0, and we get $\mathcal{E} = A_c^2 T$. Thus

$$P_{e,\text{opt}} = Q \left(\sqrt{\frac{2\mathcal{E}}{N_0}} \right) = Q \left(\sqrt{\frac{2A_c^2 T}{N_0}} \right)$$